

## Example: Prediction

EE363  
Stanford University

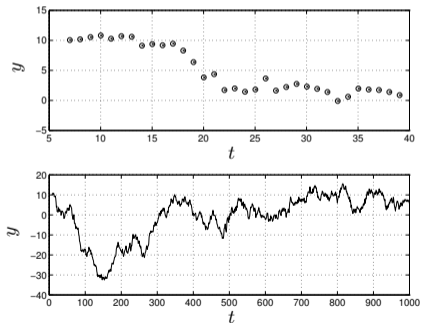
## Estimation / prediction

random time-series  $y$  modeled as

$$x(t+1) = Ax(t) + Bw(t), \quad y(t) = Cx(t) + Dv(t)$$

where  $w$  and  $v$  are white noises (details later)

specific example, with  $x(t) \in \mathbb{R}^{10}$  and scalar  $y(t)$ :

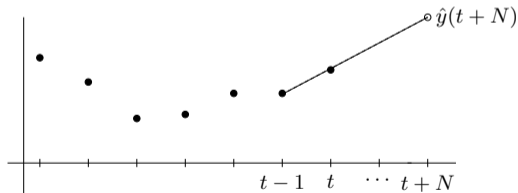


## Problem

**problem:** predict  $y(t + N)$  based on  $y(t)$ ,  $y(t - 1), \dots$   
(which obviously has many practical uses ...)

**simple method:** predict  $y(t + N)$  by *linear extrapolation* through  $y(t)$  and  $y(t - 1)$ :

$$\hat{y}(t + 1) = y(t) + N(y(t) - y(t - 1))$$

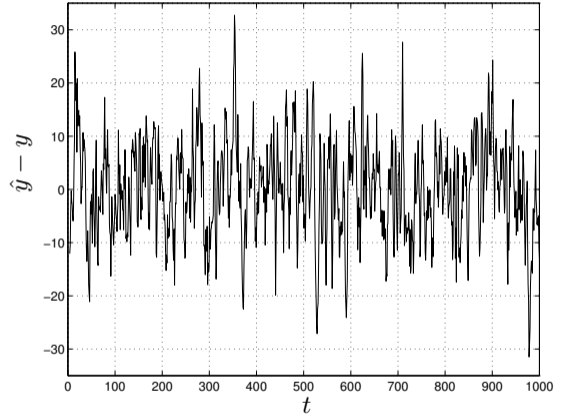


## Performance of linear extrapolation

how well does it do? (with  $N = 4$ )

RMS prediction error is 9.03 (RMS  $y$  is 11.11)

*i.e.*, 81% RMS prediction error



## Better approach

in this course we'll study the **optimal** predictor  
(which happens to be a linear system . . .)

prediction error with optimal predictor (same scale):

optimal RMS prediction error is 2.17

*i.e.*, 20% RMS prediction error

